

**Kontinuitätsgleichung**, kartesische Koordinaten:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

**Navier-Stokes-Gleichungen**, kartesische Koordinaten

$$\text{x-Richtung: } \rho \left( \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = - \frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \rho g_x$$

$$\text{y-Richtung: } \rho \left( \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = - \frac{\partial p}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) + \rho g_y$$

$$\text{z-Richtung: } \rho \left( \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) = - \frac{\partial p}{\partial z} + \mu \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) + \rho g_z$$

**Kontinuitätsgleichung**, Zylinderkoordinaten:

$$\frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial v_z}{\partial z} = 0$$

**Navier-Stokes-Gleichungen**, Zylinderkoordinaten

Radialrichtung (r):

$$\rho \left( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\varphi}{r} \frac{\partial v_r}{\partial \varphi} - \frac{v_\varphi^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = - \frac{\partial p}{\partial r} + \mu \left\{ \frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right] + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \varphi^2} - \frac{2}{r^2} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial^2 v_r}{\partial z^2} \right\} + \rho g_r$$

Umfangsrichtung (φ):

$$\rho \left( \frac{\partial v_\varphi}{\partial t} + v_r \frac{\partial v_\varphi}{\partial r} + \frac{v_\varphi}{r} \frac{\partial v_\varphi}{\partial \varphi} + \frac{v_r v_\varphi}{r} + v_z \frac{\partial v_\varphi}{\partial z} \right) = - \frac{1}{r} \frac{\partial p}{\partial \varphi} + \mu \left\{ \frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial}{\partial r} (r v_\varphi) \right] + \frac{1}{r^2} \frac{\partial^2 v_\varphi}{\partial \varphi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \varphi} + \frac{\partial^2 v_\varphi}{\partial z^2} \right\} + \rho g_\varphi$$

Achsrichtung (z):

$$\rho \left( \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\varphi}{r} \frac{\partial v_z}{\partial \varphi} + v_z \frac{\partial v_z}{\partial z} \right) = - \frac{\partial p}{\partial z} + \mu \left\{ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \varphi^2} + \frac{\partial^2 v_z}{\partial z^2} \right\} + \rho g_z$$

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**Navier-Stokes-Gleichungen**, kartesische Koordinaten

$$\text{x-Richtung: } \rho \left( \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = -\frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \rho g_x$$

$$\text{y-Richtung: } \rho \left( \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = -\frac{\partial p}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) + \rho g_y$$

$$\text{z-Richtung: } \rho \left( \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) + \rho g_z$$

**Kontinuitätsgleichung**, Zylinderkoordinaten:

$$\frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z} = 0$$

**Navier-Stokes-Gleichungen**, Zylinderkoordinaten

Radialrichtung (r):

$$\rho \left( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\phi}{r} \frac{\partial v_r}{\partial \phi} - \frac{v_\phi^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial p}{\partial r} + \mu \left\{ \frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right] + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \phi^2} - \frac{2}{r^2} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial^2 v_r}{\partial z^2} \right\} + \rho g_r$$

Umfangsrichtung ( $\phi$ ):

$$\rho \left( \frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\phi}{r} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi}{r} + v_z \frac{\partial v_\phi}{\partial z} \right) = -\frac{1}{r} \frac{\partial p}{\partial \phi} + \mu \left\{ \frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial}{\partial r} (r v_\phi) \right] + \frac{1}{r^2} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \phi} + \frac{\partial^2 v_\phi}{\partial z^2} \right\} + \rho g_\phi$$

Achsrichtung (z):

$$\rho \left( \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\phi}{r} \frac{\partial v_z}{\partial \phi} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left\{ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \phi^2} + \frac{\partial^2 v_z}{\partial z^2} \right\} + \rho g_z$$

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$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

**Navier-Stokes-Gleichungen**, kartesische Koordinaten

$$\text{x-Richtung: } \rho \left( \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = -\frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \rho g_x$$

$$\text{y-Richtung: } \rho \left( \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = -\frac{\partial p}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) + \rho g_y$$

$$\text{z-Richtung: } \rho \left( \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) + \rho g_z$$

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$$\frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial v_z}{\partial z} = 0$$

**Navier-Stokes-Gleichungen**, Zylinderkoordinaten

Radialrichtung (r):

$$\rho \left( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\varphi}{r} \frac{\partial v_r}{\partial \varphi} - \frac{v_\varphi^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial p}{\partial r} + \mu \left\{ \frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right] + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \varphi^2} - \frac{2}{r^2} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial^2 v_r}{\partial z^2} \right\} + \rho g_r$$

Umfangsrichtung (φ):

$$\rho \left( \frac{\partial v_\varphi}{\partial t} + v_r \frac{\partial v_\varphi}{\partial r} + \frac{v_\varphi}{r} \frac{\partial v_\varphi}{\partial \varphi} + \frac{v_r v_\varphi}{r} + v_z \frac{\partial v_\varphi}{\partial z} \right) = -\frac{1}{r} \frac{\partial p}{\partial \varphi} + \mu \left\{ \frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial}{\partial r} (r v_\varphi) \right] + \frac{1}{r^2} \frac{\partial^2 v_\varphi}{\partial \varphi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \varphi} + \frac{\partial^2 v_\varphi}{\partial z^2} \right\} + \rho g_\varphi$$

Achsrichtung (z):

$$\rho \left( \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\varphi}{r} \frac{\partial v_z}{\partial \varphi} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left\{ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \varphi^2} + \frac{\partial^2 v_z}{\partial z^2} \right\} + \rho g_z$$